

Spatial Scalable Video Compression Using H.264

Divya. R ¹, Athilakshmi², Fahmitha Soukath. J ³, Gayathri. P ⁴

Department of Electronics communication and engineering

Dr.S.J.S Paul Memorial College of Engineering and Technology, Puducherry, India.

Abstract: H.264 is a standard was jointly developed by ITU-T and ISO/IEC Moving Picture Expert Group. The main goal of H.264 is to achieve spatial scalability and to improve the compression performance compared to other standards. The H.264 is used to encode the video in a spatial manner, so that the number of the frames is reduced and its size is being reduce thus it achieve scalability. The compression techniques in H.264 will compress the video from its original size and produce an efficient output. The video format used in this software is QCIF video and it is encoded and decoded using the H.264 design.

Keywords: Advanced Video Coding(AVC),H.264,High Efficiency Video Coding(HEVC),Joint Collaborative Team-Video Coding(JCT-VC),Moving Pictures Expert Group(MPEG).

I. Introduction

In electronics engineering, video processing is a particular case of signal processing, which often employs video filters and where the input and output signals are video files or video streams. Video compression algorithms ("codecs") manipulate video signals to dramatically reduce the storage and bandwidth required while maximizing perceived video quality. The standardization techniques has become higher priority because only a standard can reduce the cost of video compression codecs. The major problem in high compression video coding is the operational control of the encoder. This can be compounded by varying the content and motion found in typical video sequences.H.264 is a method and format for video compression process of converting digital video into a format that takes up less capacity when it is stored or transmitted.

II. H.261 System

H.261 is a compression has been specifically designed for video telecommunication application. It was developed by CCITT in 1988-1990. It is meant for video conferencing, video telephone application over ISDN telephone lines. The base lines of ISDN is 64 kbps and integral multiple of (P×64).It is a ITU video compression standard . It supports only two video frame sizes CIF(352×288 luma with 176×144 chroma) and QCIF(176×144 luma with 88×72 chroma) using 4:2:0 sampling scheme.

H.261 encoder model

H.261 defines two types of coding. Intra coding where blocks of 8x8 pixels each are encoded only with reference to themselves and they are sent directly to the block transformation process. A prediction error is calculated between a 16x16 pixel region (macroblock) and the (recovered) correspondent macroblock in the previous frame. Prediction error of transmitted blocks (criteria of transmission is not standardized) are then sent to the block transformation process. H.261 supports motion compensation in the encoder in which a search area is constructed in the previous (recovered) frame to determine the best reference macroblock . In block transformation, intra coded frames as well as prediction errors will be composed into 8x8 blocks. Each block will be processed by a two-dimensional FDCT function. If this sounds expensive, there are fast table driven algorithms and can be done in software quite easily, as well as very easily in hardware.

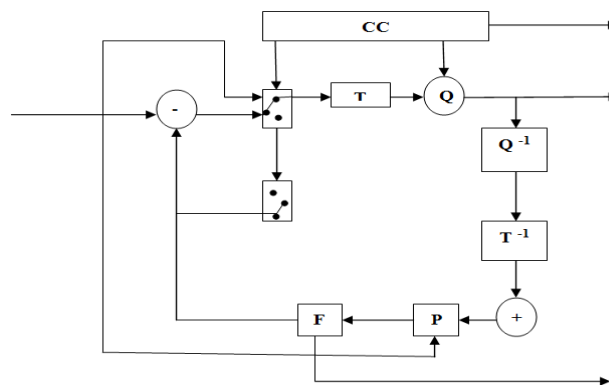


Fig.1. Block Diagram of H.261 Encoder System.

The advantage in H.261 is the maximum frame rate is 30 frames per second but it can be reduced depending on the application and bandwidth. It supports both temporal and spatial redundancy of video sequences to achieve high compression ratio. The disadvantage in H.261 is that it does not have good quality as H.263 and it cannot support for lower end machines.

III. H. 263 System

A. Encoder

Video coding aims at providing a compact representation of the information in the video frames by removing spatial redundancies that exist within the frames, and also temporal redundancies that exist between successive frames. As in the case of the H.261 standard, the H.263 standard is based on using the discrete cosine transform (DCT) to remove spatial redundancies, and motion estimation and compensation to remove temporal redundancies. When a source frame is coded using the DCT, the encoder is said to be operating in the intra coding mode, and the corresponding encoded frame is called an I-picture. In the case where temporal prediction is used, the encoder is said to be operating in the inter coding mode, and the corresponding encoded frame is called a P-picture. A block diagram for a typical encoder is given in Fig 2.

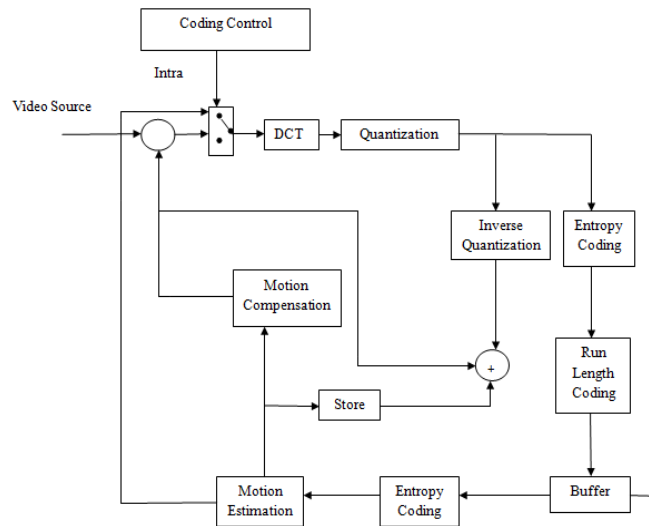


Fig.2. block diagram of H.263 Encoder.

B. Decoder

A block diagram of a typical decoder is shown in Figure 3. In the case of an intracoded macroblock, the encoder performs only the inverse quantization and inverse DCT operations to reconstruct the original macroblock. The reconstructed macroblock is then used in the reconstructed frame.

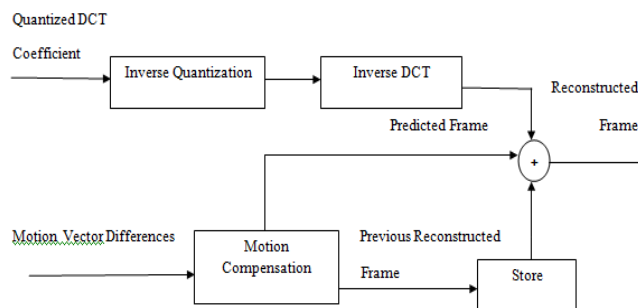


Fig.3. Block diagram of typical decoder.

IV. H.264 System

H.264 is a video compression format that is currently one of the most commonly used formats for recording ,compression and distribution of video content.

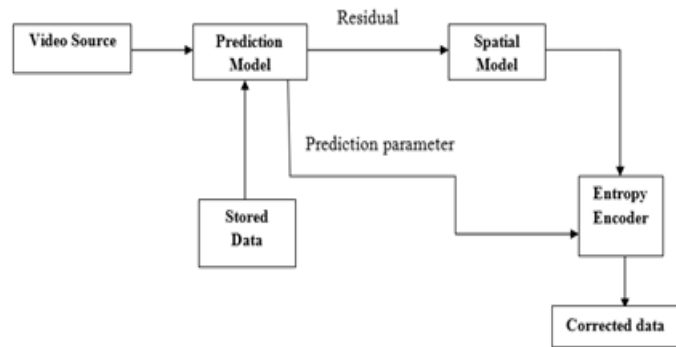


Fig.4 H.264 Encoder module.

A video CODEC Fig.4 encodes a source image or video sequence into a compressed form and decodes this to produce a copy or approximation of the source sequence. A video encoder Fig.4 consists of three main functional units: a prediction model, a spatial model and an entropy encoder. The input to the prediction model is an uncompressed ‘raw’ video sequence. The prediction model attempts to reduce redundancy by exploiting the similarities between neighboring video frames and neighboring image samples, typically by constructing a prediction of the current video frame or block of video data. The output of the prediction model is a residual frame, created by subtracting the prediction from the actual current frame, and a set of model parameters indicating the intra prediction type or describing how the motion was compensated. The residual frame forms the input to the spatial model which makes use of similarities between local samples in the residual frame to reduce spatial redundancy.

V. Stimulation Parameter

```

Command Prompt

Frame  Bit/pic  QP  SnrV  SnrU  SnrD  Time(ms)  MEI(ms)  Frn/Fld  Ref
-----
00000(NUB)  168
00000(I,DR)  21096  28  37.526  41.289  42.851  450  0  FRM  3
00002( P )  8200  28  36.824  40.943  42.317  10708  10117  FRM  2
00001( B )  2320  30  36.311  41.027  42.543  37518  36912  FRM  0

Total Frames: 3
Leaky BucketRateFile does not have valid entries.
Using rate calculated from avg. rate
Number Leaky Buckets: 8
  Rmin  Bmin  Fmin
316140  21096  21096
395160  21096  21096
474180  21096  21096
553200  21096  21096
632220  21096  21096
711240  21096  21096
790260  21096  21096
869280  21096  21096
-----
Average data all frames
-----
Total encoding time for the seq. : 48.676 sec (0.06 fps)
Total ME time for sequence      : 47.029 sec

V < PSNR (dB), cSNR (dB), MSE > : ( 36.887, 36.859, 13.40333 )
U < PSNR (dB), cSNR (dB), MSE > : ( 41.087, 41.084, 5.06602 )
D < PSNR (dB), cSNR (dB), MSE > : ( 42.570, 42.565, 3.60264 )

Total bits          : 31784 (I 21096, P 8200, B 2320 NUB 168)
Bit rate (kbit/s) @ 30.00 Hz : 317.84
Bits to avoid Startcode Emulation : 25
Bits for parameter sets : 168
Bits for filler data : 0

Exit JM 18 (PRExt) encoder ver 18.6
C:\Users\Ranachandran\Desktop\jmi18.6\JM\bin>
    
```

```

C:\Users\Ranachandran\Desktop\jn18.6\JM\bin>ldecod.exe -d decoder_main.cfg
Setting Default Parameters...
Parsing Configfile decoder_main.cfg

*****
* Decoder Parameters
*****
Parameter InputFile = test.264
Parameter OutputFile = test_dec.yuv
Parameter RefFile = test_rec.yuv
Parameter UrateU = 1
Parameter FileFormat = 0
Parameter RefOffset = 0
Parameter POCScale = 2
Parameter DisplayDecParams = 1
Parameter ConcealMode = 0
Parameter RefPOCGap = 2
Parameter POCGap = 2
Parameter Silent = 0
Parameter IntraProfileDeblocking = 1
Parameter DecFrmNum = 0
Parameter DecodedAllLayers = 0
Parameter DPBPLUS0 = 1
Parameter DPBPLUS1 = 0
*****
----- JM 18.6 (PRExt) -----
POC must = frame# or field# for SNRs to be correct
-----
Frame      POC  Pic#  QP   SnrY   SnrU   SnrV   Y:U:V  Time(ms)
-----
00000(I DR)  0    0    28   0.0000 0.0000 0.0000 4:2:0   94
00002( P )  4    1    28   0.0000 0.0000 0.0000 4:2:0   44
00001( b )  2    2    30   0.0000 0.0000 0.0000 4:2:0   21
-----
Average SNR all Frames
Snr Y(dB) : 0.00
Snr U(dB) : 0.00
Snr V(dB) : 0.00
Total decoding time : 0.160 sec (18.750 fps)[3 frm/160 ms]
-----
Exit JM 18 (PRExt) decoder, ver 18.6
Output status file          : log.dec
3 frames are decoded.

C:\Users\Ranachandran\Desktop\jn18.6\JM\bin>_

```

In this paper we use JM (Joint Model) Software to stimulate the output of H.264. The output is generated by giving a QCIF format of video sequence as input and the output will be H.264 format video data. Here the encoded and decoded output values of the given sequence is compared using various parameters. The video sequence consist of mainly three frames namely Y-frame, U-frame, and V-frame. At the decoder part of H.264 the input format of video is H.264 and the output is the QCIF form of video. The display parameters of the YUV frames or fields and their decoding time of each frames were given. The following table 1 and table 2 shows the parameter comparison in encoder and decoder of H.264.

Table 1 Comparison of SNR, CSNsR, MSE

	PSNR	CSNR	MSE
Y	36.887	36.859	13.40333
U	41.087	41.084	5.06602
V	42.570	42.565	3.6024

The table 1 shows the signal to noise ratio and channel signal to noise ratio of YUV frames and its Mean Square Error rate.

FRAME	BIT/PIC	QP	SNR Y	SNR U	SNR V	TIME
NVB	168	-	-	-	-	-
IDR	2109	28	37.5	41.2	42.8	450
P	8200	28	36.8	40.9	42.3	10708

Table 2 Comparison of various parameters.

The table 2 shows the bit/pic rate, QP and SNR values for various parameters in the video sequences.

VI. Comparison Of Pervious Standards

The H.261 coding algorithm was designed to operate at video bitrates between 40kpbs and 2mbps. H.261 supports two video sizes CIF and QCIF using 4:2:0 sampling scheme. H.263 is a video compression standard originally designed as a low bit rate compressed format for video conferencing. The next enhanced video codec developed by ITU-T VCEG after H.263 is the H.264 standard, also known as AVC and MPEG 4 it provides a significant improvement in capability beyond H.263.

Table 3 Comparison of H.261,H.263&H.264

Application	Data Rate	Video Standard
Digital television broadcasting	2-5 mbps 10-20 mbps for HD	MPEG-2 H.264/AVC
DVD video,HD-DVD,Blue ray disk	4 to 8 mbps 10 to 20 mbps	MPEG-2 H.264/AVC, VC-1
Internet video streaming	20 to 600 kbps	Proprietary similar to H.263, MPEG-4 of H.264/AVC, VC-1
Video conferencing, telephony	20 to 320 kbps	H.261,H.263, H.264/AVC
Video over 3G wireless	20 to 200 kbps	H.263, MPEG-4,H.264/AVC, VC-1

VII. Conclusion

The result of this paper indicate that the H.264 standard can provide a significant amount of increased coding efficiency. The reduction is achieved by the video coding design H.264 using JM Software. . The video sequence we use in this is quarter video with 176×144 size. This is achieved by removing the similar neighboring frames and compress the space and improve scalability of the video sequence It provides 31 to 35% of efficiency and bit rate reduction when compared to the previous standards.

Reference

- [1]. H. Everett, "Generalized Lagrange multiplier method for solving problems of optimum allocation of resources," *Oper. Res.*, vol. 11, pp. 399–417, May–Jun. 1963.
- [2]. S.-W. Wu and A. Gersho, "Enhanced video compression with standardized bitstream syntax," in *Proc. IEEE Int. Conf. Acoust., Syst., Signal Process.*, vol. I. Apr. 1993, pp. 103–106.
- [3]. ITU-T and ISO/IEC JTC 1, *Generic Coding of Moving Pictures and Associated Audio Information—Part 2: Video*, ITU-T Rec. H.262 and ISO/IEC 13818-2 (MPEG-2 Video), version 1, 1994.
- [4]. K. Ramchandran and M. Vetterli, "Rate-distortion optimal fast thresholding with complete JPEG/MPEG decoder compatibility," *IEEE Trans. Image Process.*, vol. 3, no. 5, pp. 700–704, Sep. 1994.
- [5]. G. J. Sullivan and T. Wiegand, "Rate-distortion optimization for video compression," *IEEE Signal Process. Mag.*, vol. 15, no. 6, pp. 74–90, Nov. 1998.
- [6]. J. L. Mitchell, W. B. Pennebaker, C. E. Fogg, and D. J. LeGall, *MPEG Video Compression Standard*. Dordrecht, The Netherlands: Kluwer Academic, 2000.
- [7]. E.-H. Yang and X. Yu, "Rate distortion optimization for H.264 inter frame coding: A general framework and algorithms," *IEEE Trans. Image Process.*, vol. 16, no. 7, pp. 1774–1784, Jul. 2007.
- [8]. G. J. Sullivan and J.-R. Ohm, "Recent developments in standardization of High Efficiency Video Coding (HEVC)," in *Proc. 33rd SPIE Appl. Dig. Image Process.*, vol. 7798. Aug. 2010, pp. 7798–7830.
- [9]. T. Wiegand, J.-R. Ohm, G. J. Sullivan, W.-J. Han, R. Joshi, T. K. Tan, and K. Ugur, "Special section on the joint call for proposals on High Efficiency Video Coding (HEVC) standardization," *IEEE Trans. Circuits Syst. Video Technol.*, vol. 20, no. 12, pp. 1661–1666, Dec. 2010.
- [10]. P. Hanhart, M. Rerabek, F. De Simone, and T. Ebrahimi, "Subjective quality evaluation of the upcoming HEVC video compression standard," in *Proc. SPIE Appl. Digital Image Process. XXXV*, vol. 8499. Aug. 2012, pp. 84990V-1–84990V-13.
- [11]. B. Bross, W.-J. Han, J.-R. Ohm, G. J. Sullivan, and T. Wiegand, *High Efficiency Video Coding (HEVC) Text Specification Draft 9*, Joint Collaborative Team on Video Coding (JCT-VC) of ITU-T SG 16 WP 3 and ISO/IEC JTC 1/SC 29/WG 11, document JCTVC-K1003, Shanghai, China, Oct. 2012.
- [12]. G. J. Sullivan, J.-R. Ohm, W.-J. Han, and T. Wiegand, "Overview of the High Efficiency Video Coding (HEVC) standard," *IEEE Trans. Circuits Syst. Video Technol.*, vol. 22, no. 12, pp. 1648–1667, Dec. 2012.